Deep Generative Models: Transformers

Fall Semester 2024

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Taxonomy of Generative Models

Autoregressive Models

- Many kinds of models
	- Markov Chains
	- Hidden Markov Models
	- Markov Random Fields
	- Linear Dynamical Systems
	- Recurrent Neural Networks
	- **Transformers**
- Last lecture
	- **Model**: Introduced the vanilla RNN architecture
	- **Inference**: Unfolding
	- **Training**: Backpropagation Through Time
	- **Variants of RNNs**: LSTMs, GRUs
	- **Seq2Seq**: Machine Translation, Image Captioning
	- **Attention Mechanism**: Soft and Hard Attention

Last Lecture: Why RNNs fall short?

- **Hard to capture long-term dependencies**
	- Require modification to architectures
- **Hard to train** due to vanishing and exploding Gradients
- **Hard to process in parallel** due to sequential nature
- **Transformers: A non-recurrent solution that solely relies on "attention":**

• **No reliance on recurrence:**

- Transformers capture dependencies across all input *tokens (words)* simultaneously, processing the entire sequence at once.
- This allows for parallel computation, unlike RNNs that rely on sequential processing.
- **Captures global dependencies:**
	- The attention mechanism enables modeling of long-range dependencies without the vanishing gradient problem.

Recall the Translate and Align Model in RNNs

• Decoder: context vector c_t is computed as a weighted sum of the hidden states z_j :

$$
c_t = \sum_{j=1}^{T_x} \gamma_{tj} z_j \qquad \gamma_{tj} = \frac{\exp(e_{tj})}{\sum_{k=1}^{T_x} \exp(e_{tk})} \qquad e_{tj} = a(s_{t-1}, z_j)
$$

Context vector Weights of hidden states Alignment model

• Here:

- *a* is called the **Alignment model**
	- Computes how well the inputs around position j and the output at position t match
	- Typically chosen to be a feedforward neural network
- γ_{tj} is the probability that the target word y_t is aligned to, or translated from, a source word x_j .
- c_t is the expectation of the hidden state w.r.t. the distribution γ_{tj} .

From RNNs to Transformers

- Let's keep what is good from Align & Translate:
	- Use encoder to learn latent representation of source sentence
	- Use decoder to learn latent representation of target sentence
	- Align the latent representations of the source/target sentences and form **global contexts**
	- Use decoder to map contexts to target sentences
- Let's recap our setting: Machine Translation
	- We are given a sentence, a sequence of *tokens* (words) as input, represented by $x = (x_1, ..., x_T)$. We want to build an architecture that takes a sentence as input and produces a translated target sentence $y = (y_1, ..., y_T)$ as output.

Transformer

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Word to Word Embedding

- First, just like any RNN language tasks, we convert our one-hot vector into embeddings through a word embedding
- Given a sentence, a sequence of one-hot vectors, $\tilde{x} = (\tilde{x}_1, ..., \tilde{x}_T), \tilde{x}_t \in \{0, 1\}^N$
- We obtain the embedding for each word by $x_t=E\tilde{x}_t$
- Again $E \in \mathbb{R}^{d \times N}$ is the embedding matrix, and can be pre-trained or learned end-to-end
- In the context of transformers, x_t is also known as a *token.*

What about the order?

- In RNNs, the recurrence plays a role in telling us the order of the words in a sentence. But now, we won't have that, since we lose the recurrence
- Simple example:
	- {*I, do, not, like, apples, and, you, like, oranges*} and {*you, like, apples, and, I, do, not, like, oranges*}
	- Since they contain the same words, they are actually the same set!
- Need method to encode position of an entity that
	- Outputs a unique encoding for each position
	- Distance between any two positions should be consistent across sentences with different lengths
	- Generalize to longer sentences without any efforts
	- Its values should be bounded

Positional Encoding: Why vectors instead of indexes?

- Positional encoding describes the location or position of an entity in a sequence
- Each position is assigned a unique representation

Positional Encoding Matrix for the sequence 'I am a robot'

- Why not just use the index?
	- For long sequences, the indices can grow large in magnitude.
	- If you normalize the index value to lie between 0 and 1, it can create problems for variable length sequences as they would be normalized differently

Positional Encoding: Intuition

- Suppose you want to represent a number in binary
	- The lowest bit alternates with every number
	- The second-lowest bit alternates every two numbers, and and and higher bits continue this pattern.
- But using binary values would be a waste of space
- Instead, we can use their continuous counterparts: sinusoidal functions.
- By decreasing their frequencies, we replicate the behavior of binary bits:
	- Higher frequencies alternate more rapidly, similar to the lower bits in binary (e.g., red bits).
	- Lower frequencies alternate more slowly, similar to the higher bits in binary (e.g., orange bits).

Positional Encoding

- To convey the ordering information, we use **Positional Embeddings** $P \in \mathbb{R}^{d \times T}$
- In "Attention is All you Need", authors suggested

- Let $x = [x_1, ..., x_T] \in \mathbb{R}^{d \times T}$ be the (row) matrix of tokens concatenated together
- Positional Embedding gets added to the input directly to the set of tokens: $x^{(0)} = x + P \in \mathbb{R}^{d \times T}$
- We use superscript (0) to denote the input, zero-th layer

Encoder Block

- Just like in the Attend & Align model, we have an encoder that turns input embeddings into hidden embeddings
- The main components of an **Encoder Block** is
	- Multi-Head Attention
	- LayerNorms
	- Feedforward Neural Networks
	- Skip Connections
- Let's break down the Multi-Head Attention!

Self-Attention

- Focuses on important parts of the input by weighing the relevance of each token to the others.
	- What does "it" in the sentence "The animal didn't cross the street because **it** was too tired." refer to?
	- Is it referring to the street or to the animal?
- Self-attention allows each token to attend to every other token in the sequence, helping the model capture context and relationships between words.
	- When processing "it", the model uses attention to understand that "it" refers to "animal."
- In RNNs, a hidden state carries context from previous tokens, but attention mechanisms allow direct access to all tokens, without relying on a sequential flow.

Self-Attention

- Given the input embeddings $x = [x_1, ..., x_T]$, we generate three matrices:
	- Query matrix Q Key matrix K Value matrix V
- Input embeddings are transformed into these matrices by multiplying the embeddings by three weight matrices W^{Q} , W^{K} , W^{V} that we learn during the training process. X **W_Q**
- Analogy for Query, Key, and Value: Library System
	- Imagine you're looking for information on a topic (**query**)
	- Each book has a summary (**key**) to help you identify if it contains relevant information.
	- Once you find a match, you access the book to get the detailed information (**value**) you need.
	- In Attention, we do a "soft match" across multiple books, combining relevant information from each book in proportion to how relevant it is (e.g., book 1 is most relevant, then book 2, etc).

Self-Attention

- Calculate the attention score by taking the dot product of Q and K^T .
- Divide the scores by $\sqrt{d_k}$, where d_k is the dimension of the hidden embedding, to ensure the variance of the dot product does not grow with d_k , leading to unstable attention mechanism.
- Apply the softmax function to the scaled scores, turning them into probabilities.
- Multiply softmax scores by V to obtain the final attention output.
- The self-attention, thus, is defined as:

• The term "self" comes from the fact that Q, K, V are all derived from the same input sequence $x = [x_1, ..., x_T]$

Multi-Head Self-Attention (MSA)

action of

• **Multi-head Self Attention (MSA)** extends Self-Attention by introducing multiple independent attention heads, each focusing on different types of relationships.

> "The animal didn't **cross** the street because it was too tired." target inverts

cause

• Each head is considered as one copy of a single Self Attention, with additional weight matrices W_i^Q , W_i^K , W_i^V for each head, indexed by i : ınea

$$
MSA(Q, K, V) = [SA(Q_1, K_1, V_1), ..., SA(Q_h, K_h, V_h)]W_0
$$

$$
Q_i = W_i^Q Q \qquad K_i = W_i^K K \qquad V_i = W_i^V V
$$

- Where $W_O \in \mathbb{R}^{(h \cdot d_v) \times d}$ is the weighting matrix between all attention heads, and W_i^Q , W_i^K , $W_i^{\overline{V}}$ are weight matrices of query, key value for each head $i = 1, ..., h$
- **Multi-Head Cross Attention (MCA)** applies the same mechanism in the context where the *queries*, *keys*, and *values* might come from different sources.

Residual Connection & Layer Normalization

- **Residual Connection:** combines the input with the output of a sub-layer (either self-attention or feed forward).
	- It allows the gradients to flow through the network directly, bypassing non-linear transformations.

 $Output = LN(x + SubLayer(x))$

- **LayerNorm** normalizes the inputs across the features instead of the batch dimension.
	- This ensures consistent scaling across layers, leading to more stable training.

$$
LN(x) = \gamma \cdot \frac{x - \mu}{\sigma} + \beta
$$

Encoder Block Summarized

• Putting everything together mathematically, the encoder block can be described by

$$
\hat{x}^{(l)} = LN(MSA(x^{(l-1)}, x^{(l-1)}, x^{(l-1)}) + x^{(l-1)})
$$

$$
x^{(l)} = LN(FFN(\hat{x}^{(l)}) + \hat{x}^{(l)})
$$

where FFN is a feed forward neural network and LN denotes Layer Norm

- Note that the input and output dimension of the encoder block is the same - $\mathbb{R}^{T \times d}$
- We can stack encoder blocks together to make it *deeper*
- The output is like the input a collection of tokens, but **in context with other tokens**

Decoder Block

- Now, we are going to switch gears into the decoder blocks
- At a high level,
	- During inference, the decoder will take in a <BOS> (beginning of sentence) token as input, and recursively predict the next word until the <EOS> (end of sentence) token is predicted
	- Just like our previous methods for machine translation, the decoder should take in *context* from the encoder to predict what the next token should be

Decoder Block: Attention Layers

- In the Encoder, each block consists of only *one* Multi-Head Self-Attention layer.
- In the Decoder, each block consists *two layers*:
	- The first one is a Masked Multi-Head Self-Attention with tokens from input (ignore "masked" part for now)
		- *Allows each token to attend to previous ones in the sequence.*

 $\widehat{\mathbf{y}}^{(l)} = \text{LN}\big(\text{MaskedMSA}\big(\mathbf{y}^{(l-1)}, \mathbf{y}^{(l-1)}, \mathbf{y}^{(l-1)}\big) + \mathbf{y}^{(l-1)}\big)$

- The Second one is a Multi-Head *Cross* Attention with key and values matrices from the output of the encoder, and query matrix from the previous Multi-Head Self-Attention
	- *Allows the decoder to focus on relevant part of encoded input*

$$
\widetilde{\mathbf{y}}^{(l)} = \text{LN}\big(\text{MCA}\big(\widehat{\mathbf{y}}^{(l-1)}, \mathbf{x}^{(N)}, \mathbf{x}^{(N)}\big) + \widehat{\mathbf{y}}^{(l-1)}\big)
$$

• $\chi^{(N)}$ is the output of the encoder (composed of N encoder layers)

Decoder Block: Summarized

• Summarizing a forward pass of the Decoder Block, along with Layer Norms and Feedforward Networks like the Encoder:

$$
\hat{y}^{(l)} = LN(MaskedMSA(y^{(l-1)}, y^{(l-1)}, y^{(l-1)}) + y^{(l-1)})
$$

$$
\tilde{y}^{(l)} = LN(MCA(\hat{y}^{(l-1)}, x^{(N)}, x^{(N)}) + \hat{y}^{(l-1)})
$$

$$
y^{(l)} = LN(FFN(\tilde{y}^{(l)}) + \tilde{y}^{(l)})
$$

Decoder Block: Masked?

• Summarizing a forward pass of the Decoder Block, along with Layer Norms and Feedforward Networks like the Encoder:

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\tilde{y}^{(l)} = LN(MCA(\hat{y}^{(l-1)}, x^{(N)}, x^{(N)}) + \hat{y}^{(l-1)})
$$

$$
y^{(l)} = LN(FFN(\tilde{y}^{(l)}) + \tilde{y}^{(l)})
$$

• But, what does the "Masked" in Masked Multi-Head Attention mean?

Decoder Block: Masked MHA

- Just liked Multi-Head Attention, MaskedMHA calculates attention scores using a scaled dotproduct of Query and Key vectors, and normalizes these scores with a softmax function to obtain attention weights.
- During training, MMHA applies masks on the attention matrices. This is important to preserve the autoregressive property, where each token is predicted based on the preceding tokens only.

Training

- Training the Transformer shares similar intuition with other Seq2Seq models. The transformer uses masked self-attention in the decoder, which doesn't depend on future words in the sequence.
- The objective is to minimize the prediction error for the next word of the target sequence. For example, when translating "Soy un estudiante" to "I am a student", the training of transformer (θ) is to minimize the KL divergence of the target sequence prediction (y) and the ground truth (x) across the dataset (D).

$$
\mathcal{L} = -\sum_{(x,y)\in\mathcal{D}} \log P(y|x;\theta)
$$

Trained Model Outputs

Attention Visualization: Long distance dependency

- Earlier we saw the sentence: "The animal didn't cross the street because **it** was too tired."
- What does "**it**" in this sentence refer to? The visualization of self-attention shows the association of "it" with beginning parts like "The animal".

- On the right we see another visualization showing how different words in a longer sentence relate to each other.
- Check out this interactive [visualization.](https://colab.research.google.com/github/tensorflow/tensor2tensor/blob/master/tensor2tensor/notebooks/hello_t2t.ipynb)

Attention: Attention from Different Heads

- Attention heads can specialize to capture various dependencies, such as syntactic and semantic relationships.
- This allows the model to attend to different types of causalities between words in a sentence.

RNNs vs. Transformers

Recurrent Neural Network

- Handle Sequential Data
- Learn Sequential Dependencies
- Each time step depends on the previous one

Transformers

- Handle Sequential Data
- Learn Sequential Dependencies
- Use self-attention to capture global context

Multi-Head Attention

RNNs vs. Transformers

Recurrent Neural Network

- (-) Learning long-range dependences is challenging due to recurrent structure
	- Can be aided by specialized architectures like LSTM and GRU
	- Suffer from training issues such as vanishing gradient

Transformers

- (+) Attention mechanism better captures long-range dependences
	- Able to handle both global context and local context
	- No vanishing gradient issues

- (-) Hard to scale up because each time step depends on the previous one
- (+) Usually smaller number of parameters, does not require lots of data to train
- (+) Processes tokens in parallel, makes it efficient for training on GPUs
- (-) Usually large number of parameters, requires lots of data to train

Iterations of Transformers

- Natural Language Processing
- BERT (Bidirectional Encoder Representations from Transformers)
- GPT (Generative Pre-trained Transformer)
- RoBERTa (Robustly Optimized Bert Pre-training)
- T5 (Text-to-Text Transfer Transformer)
- Vision
- Vision Transformer
- Swin Transformer, Pyramid Vision Transformer