Deep Generative Models Background

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Outline

• Basics of Probability, Statistics, Information Theory

- Discrete and Continuous Distributions, Independence
- Marginals, Conditionals & Example for a Gaussian
- Entropy, Mutual Information, KL Divergence
- Generative vs Discriminative Models
- Learning Generative Models
 - Learning Criterion: Maximum Likelihood Estimation
 - Learning Algorithm: Stochastic Gradient Descent
- Classes of Generative Models
 - Gaussian Models: Closed form Solution
 - General Models: Need for Structure
 - Taxonomy of Models
 - Latent variable models, Autoregressive models, Energy based models

- Review of Probability and Statistics
- We define some basic notations
- Data $x \in \mathbb{R}^{D}$ follows some data distribution $x \sim p(x)$
- If x is discrete, then p(x) is a probability mass function, taking on discrete values $k \in \mathcal{X} = \{1, ..., N\}$
- If x is continuous, then p(x) is a probability density function
- Independence: x and y are independent if and only if p(x, y) = p(x)p(y)

Marginals, Conditionals

- Marginal distribution
 - In the continuous case

$$p(\mathbf{x}) = \int p(\mathbf{x}, \mathbf{y}) d\mathbf{y}$$

• Product rule $p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x}|\mathbf{y})p(\mathbf{y})$ $= p(\mathbf{y}|\mathbf{x})p(\mathbf{x})$

• In the discrete case

$$p(\boldsymbol{x}) = \sum_{\boldsymbol{y}} p(\boldsymbol{x}, \boldsymbol{y})$$

- Bayes rule $p(\mathbf{y}|\mathbf{x}) = \frac{p(\mathbf{x}|\mathbf{y})p(\mathbf{y})}{p(\mathbf{x})}$
- Conditional distribution / Bayes rule $p(\mathbf{y}|\mathbf{x}) = \frac{p(\mathbf{x}, \mathbf{y})}{p(\mathbf{x})}$

Marginal and Conditional Distribution for a Gaussian

• Assume $x \sim \mathcal{N}(x | \mu, \Sigma)$ where

$$\boldsymbol{x} = \begin{bmatrix} \boldsymbol{x}_a \\ \boldsymbol{x}_b \end{bmatrix}, \qquad \boldsymbol{\mu} = \begin{bmatrix} \boldsymbol{\mu}_a \\ \boldsymbol{\mu}_b \end{bmatrix}, \qquad \boldsymbol{\Sigma} = \begin{bmatrix} \boldsymbol{\Sigma}_a & \boldsymbol{\Sigma}_c \\ \boldsymbol{\Sigma}_c^\top & \boldsymbol{\Sigma}_b \end{bmatrix}$$

• Then, we get the following results

$$p(\mathbf{x}_{a}) = \mathcal{N}(\mathbf{x}_{a} | \boldsymbol{\mu}_{a}, \boldsymbol{\Sigma}_{a}),$$

$$p(\mathbf{x}_{a} | \mathbf{x}_{b}) = \mathcal{N}(\mathbf{x}_{a} | \hat{\boldsymbol{\mu}}_{a}, \hat{\boldsymbol{\Sigma}}_{a}), \text{ where }$$

$$\hat{\boldsymbol{\mu}}_{a} = \boldsymbol{\mu}_{a} + \boldsymbol{\Sigma}_{c} \boldsymbol{\Sigma}_{b}^{-1} (\mathbf{x}_{b} - \boldsymbol{\mu}_{b})),$$

$$\hat{\boldsymbol{\Sigma}}_{a} = \boldsymbol{\Sigma}_{a} - \boldsymbol{\Sigma}_{c} \boldsymbol{\Sigma}_{b}^{-1} \boldsymbol{\Sigma}_{c}^{\top}$$

Warm-up exercise -> HW1

Review of Information Theory

- Entropy of a random variable X
 - It captures how much "uncertainty" is present in X
 - **Definition**: $H(X) = E_{x \sim p(x)}[-\log p(x)]$
 - Continuous: $H(X) = -\int_x \log(p(x)) p(x) dx$
 - Discrete: $H(X) = -\sum_k \log(p_k) p_k$ where $p_k = P(X = k)$
 - Example: Let X be a Bernoulli random variable such that P(X = 1) = p and P(X = 0) = 1 - pThen $H(X) = -p \log p - (1 - p) \log(1 - p)$

- Conditional entropy: uncertainty of X when Y is observed
 - $H(X|Y) = \mathbb{E}_{x,y \sim p(x,y)}[-\log p(x|y)]$





Entropy of a Bernoulli variable

Review of Information Theory

Mutual Information:

- mutual dependence between X and Y
- reduction of uncertainty in X when Y is observed

$$I(X;Y) = H(X) - H(X | Y) = H(Y) - H(Y | X)$$

•
$$I(X;Y) = \mathcal{E}_{x,y \sim p(x,y)} \left[\log \left(\frac{p(x,y)}{p(x)p(y)} \right) \right]$$

- Note that if X, Y are independent, then I(X; Y) = 0
- **KL divergence** between two distributions p, q captures how similar p, q are $KL[p(x) \mid \mid q(x)] = E_{x \sim p} \left[\log \frac{p(x)}{q(x)} \right]$
 - Properties
 - Non-negativity $KL[p(x) || q(x)] \ge 0$. Equality holds iff p = q
 - In general triangle inequality and symmetry does not hold

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Statistical Generative Models

• A statistical generative model is a probability distribution p(x)



• It is generative because sampling from p(x) generates new images

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Discriminative vs. Generative Models

Discriminative: classify bedroom vs. dining room







The image X is given. **Goal**: decision boundary, via **conditional distribution over label Y**

P(Y = Bedroom | X=



Ex: logistic regression, convolutional net, etc.

Generative: generate X



Joint and conditional are related via **Bayes Rule**:

Discriminative: Y is simple; X is always given, so not need to model

Therefore it cannot handle missing data

P(Y = Bedroom | X=

P(Y = Bedroom, X=









Conditional Generative Models

Class conditional generative models are also possible:

It's often useful to condition on rich side information Y



| Caption = "A black table with 6 chairs")

A discriminative model is a very simple conditional generative model of Y:

Why Generative Models?

• Al Is Not Only About Decision Making



Fig. 1.1 An example of adding noise to an almost perfectly classified image that results in a shift of predicted label



Fig. 1.2 And example of data (*left*) and two approaches to decision making: (*middle*) a discriminative approach and (*right*) a generative approach

 Importance of uncertainty and understanding in decision making