# Deep Generative Models Background

Fall Semester 2024

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### **Outline**

#### • **Basics of Probability, Statistics, Information Theory**

- Discrete and Continuous Distributions, Independence
- Marginals, Conditionals & Example for a Gaussian
- Entropy, Mutual Information, KL Divergence
- Generative vs Discriminative Models
- Learning Generative Models
	- Learning Criterion: Maximum Likelihood Estimation
	- Learning Algorithm: Stochastic Gradient Descent
- Classes of Generative Models
	- Gaussian Models: Closed form Solution
	- General Models: Need for Structure
	- Taxonomy of Models
		- Latent variable models, Autoregressive models, Energy based models
- Review of Probability and Statistics
- We define some basic notations
- Data  $x \in \mathbb{R}^D$  follows some data distribution  $x \sim p(x)$
- If x is discrete, then  $p(x)$  is a probability mass function, taking on discrete values  $k \in \mathcal{X} = \{1, ..., N\}$
- If x is continuous, then  $p(x)$  is a probability density function
- Independence: x and y are independent if and only if  $p(x, y) = p(x)p(y)$
- Marginals, Conditionals
- Marginal distribution
	- In the continuous case

$$
p(\pmb{x}) = \int p(\pmb{x}, \pmb{y}) d\pmb{y}
$$

• Product rule  $p(x, y) = p(x|y)p(y)$  $= p(y|x)p(x)$ 

• In the discrete case

$$
p(x) = \sum_{y} p(x, y)
$$

- Bayes rule  $p(\mathbf{y}|\mathbf{x}) =$  $p(x|y)p(y)$  $p(x)$
- Conditional distribution / Bayes rule  $p(\mathbf{y}|\mathbf{x}) =$  $p(\pmb{x},\pmb{y}$  $p(x)$

Marginal and Conditional Distribution for a Gaussian

• Assume  $x \sim \mathcal{N}(x|\mu, \Sigma)$  where

$$
x = \begin{bmatrix} x_a \\ x_b \end{bmatrix}, \qquad \qquad \mu = \begin{bmatrix} \mu_a \\ \mu_b \end{bmatrix}, \qquad \qquad \Sigma = \begin{bmatrix} \Sigma_a & \Sigma_c \\ \Sigma_c^\top & \Sigma_b \end{bmatrix}
$$

• Then, we get the following results

$$
p(\mathbf{x}_a) = \mathcal{N}(\mathbf{x}_a | \boldsymbol{\mu}_a, \boldsymbol{\Sigma}_a),
$$
  
\n
$$
p(\mathbf{x}_a | \mathbf{x}_b) = \mathcal{N}(\mathbf{x}_a | \widehat{\boldsymbol{\mu}}_a, \widehat{\boldsymbol{\Sigma}}_a), \text{ where}
$$
  
\n
$$
\widehat{\boldsymbol{\mu}}_a = \boldsymbol{\mu}_a + \boldsymbol{\Sigma}_c \boldsymbol{\Sigma}_b^{-1} (\mathbf{x}_b - \boldsymbol{\mu}_b)),
$$
  
\n
$$
\widehat{\boldsymbol{\Sigma}}_a = \boldsymbol{\Sigma}_a - \boldsymbol{\Sigma}_c \boldsymbol{\Sigma}_b^{-1} \boldsymbol{\Sigma}_c^\top
$$

Warm-up exercise -> HW1

# Review of Information Theory

- **Entropy** of a random variable X
	- It captures how much "uncertainty" is present in X
	- **Definition**:  $H(X) = E_{x \sim p(x)}[-\log p(x)]$
	- **Continuous**:  $H(X) = -\int_{\mathcal{X}} \log(p(x)) p(x) dx$
	- **Discrete**:  $H(X) = -\sum_{k} \log(p_k)p_k$  where  $p_k = P(X = k)$
	- Example: Let X be a Bernoulli random variable such that  $P(X = 1) = p$  and  $P(X = 0) = 1 - p$ Then  $H(X) = -p \log p - (1 - p) \log(1 - p)$

- **Conditional entropy**: uncertainty of X when Y is observed
	- $H(X|Y) = E_{x,y \sim p(x,y)}[-\log p(x|y)]$





Entropy of a Bernoulli variable

# Review of Information Theory

#### • **Mutual Information:**

- mutual dependence between X and Y
- reduction of uncertainty in X when Y is observed

$$
I(X; Y) = H(X) - H(X | Y) = H(Y) - H(Y | X)
$$

• 
$$
I(X; Y) = E_{x,y \sim p(x,y)} \left[ \log \left( \frac{p(x,y)}{p(x)p(y)} \right) \right]
$$

- Note that if X, Y are independent, then  $I(X; Y) = 0$
- **KL divergence** between two distributions  $p$ ,  $q$  captures how similar  $p$ ,  $q$  are  $KL[p(x) || q(x)] = E_{x \sim p} \left[ \log \frac{p(x)}{q(x)} \right]$  $q(x)$ 
	- **Properties**
		- Non-negativity  $KL[p(x) || q(x)] \ge 0$ . Equality holds iff  $p = q$
		- In general triangle inequality and symmetry does not hold

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### Statistical Generative Models

• A statistical generative model is a probability distribution  $p(x)$ 



• It is generative because **sampling from**  $p(x)$  **generates new images** 

…





#### Discriminative vs. Generative Models

**Discriminative**: classify bedroom vs. dining room **Generative**: generate X







The image X is given. **Goal**: decision boundary, via **conditional distribution over label Y**



Ex: logistic regression, convolutional net, etc.



 $P(Y = Bedroom, X = 1) = 0.0002$ 

Joint and conditional are related via **Bayes Rule**:

**Discriminative**: Y is simple; X is always given, so not need to model P(X=

Therefore it cannot handle missing data  $\blacksquare$  P

 $P(Y = Bedroom | X =$ 

$$
P(Y = Bedroom | X =
$$

 $P(Y = Bedroom, X =$ 





### Conditional Generative Models

Class **conditional generative models** are also possible:

 $P(X=\sqrt{\frac{1}{\sum_{k=1}^{n} (x_k - x_k)^2}} \mid Y = \text{Bedroom})$ 

It's often useful to condition on rich side information Y



 $P(X=\sqrt{\frac{1}{n+1}}$  | Caption = "A black table with 6 chairs")

A discriminative model is a very simple conditional generative model of Y:

$$
P(Y = Bedroom | X = \sqrt{\frac{1}{\|P\|}})
$$

# Why Generative Models?

• AI Is Not Only About Decision Making



Fig. 1.1 An example of adding noise to an almost perfectly classified image that results in a shift of predicted label



Fig. 1.2 And example of data *(left)* and two approaches to decision making: *(middle)* a discriminative approach and *(right)* a generative approach

• Importance of uncertainty and understanding in decision making